

## Journal Articles

- [J1] L. von Stumberg, P. Wenzel, Q. Khan and D. Cremers,  
**GN-Net: The Gauss-Newton Loss for Deep Direct SLAM,**  
*preprint*, 2019.

## Conference and Workshop Papers

- [C1] P. Wenzel, Q. Khan, D. Cremers and L. Leal-Taixe,  
**Modular Vehicle Control for Transferring Semantic Information Between Weather Conditions Using GANs,**  
*Conference on Robot Learning (CoRL)*, 2018.