LSD-SLAM: Large-Scale Direct Monocular SLAM Publications

[C1] J. Engel, J. Stueckler and D. Cremers, 
Large-Scale Direct SLAM with Stereo Cameras, 

[C2] D. Caruso, J. Engel and D. Cremers, 
Large-Scale Direct SLAM for Omnidirectional Cameras, 

[C3] V. Usenko, J. Engel, J. Stueckler and D. Cremers, 
Reconstructing Street-Scenes in Real-Time From a Driving Car, 

[C1] J. Engel, T. Schöps and D. Cremers, 
LSD-SLAM: Large-Scale Direct Monocular SLAM, 
*European Conference on Computer Vision (ECCV)*, September 2014, Oral Presentation.

[C2] T. Schöps, J. Engel and D. Cremers, 
Semi-Dense Visual Odometry for AR on a Smartphone, 

[C1] J. Engel, J. Sturm and D. Cremers, 
Semi-Dense Visual Odometry for a Monocular Camera, 
*IEEE International Conference on Computer Vision (ICCV)*, Sydney, Australia, December 2013.