LSD-SLAM: Large-Scale Direct Monocular SLAM Publications

[C1] J. Engel, J. Stueckler and D. Cremers,  
Large-Scale Direct SLAM with Stereo Cameras,  

[C2] D. Caruso, J. Engel and D. Cremers,  
Large-Scale Direct SLAM for Omnidirectional Cameras,  

[C3] V. Usenko, J. Engel, J. Stueckler and D. Cremers,  
Reconstructing Street-Scenes in Real-Time From a Driving Car,  

[C1] J. Engel, T. Schöps and D. Cremers,  
LSD-SLAM: Large-Scale Direct Monocular SLAM,  
European Conference on Computer Vision (ECCV), September 2014, Oral Presentation.

[C2] T. Schöps, J. Engel and D. Cremers,  
Semi-Dense Visual Odometry for AR on a Smartphone,  
International Symposium on Mixed and Augmented Reality, September 2014, Best Short Paper Award.

[C1] J. Engel, J. Sturm and D. Cremers,  
Semi-Dense Visual Odometry for a Monocular Camera,  
IEEE International Conference on Computer Vision (ICCV), Sydney, Australia, December 2013.