[B1] J. Sturm, 
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots, 
Springer 2013.

[PhD1] J. Sturm, 
Approaches to Probabilistic Model Learning for Mobile Manipulation Robots, 
University of Freiburg, Germany, May 2011, Received the Artificial Intelligence Diss- 
sertation Award 2011 (ECCAI) and the Wolfgang-Genter-Award 2011 (Uni-
versity of Freiburg); Finalist at the Georges-Giralt-Award 2012 (EURON); 
Selected for the Best Paper Track at IJCAI 2013.

[C1] C. Eppner, J. Sturm, M. Bennewitz, C. Stachniss and W. Burgard, 
Imitation Learning with Generalized Task Descriptions, 
Int. Conf. on Robotics and Automation, Kobe, Japan, May 2009.

[C2] D. Meyer-Delius, J. Sturm and W. Burgard, 
Regression-Based Online Situation Recognition for Vehicular Traffic Scenarios, 