[C1] M. Jaimez, C. Kerl, J. Gonzalez-Jimenez and D. Cremers,
**Fast Odometry and Scene Flow from RGB-D Cameras based on Geometric Clustering**,  
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2017.

[C1] M. Jaimez, J. G. Monroy and J. Gonzalez-Jimenez,
**Planar Odometry from a Radial Laser Scanner. A Range Flow-based Approach**,  
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 4479-4485, 2016.

[J1] M. Jaimez and J. Gonzalez-Jimenez,
**Fast Visual Odometry for 3-D Range Sensors**,  

[J2] M. Jaimez, J. L. Blanco Claraco and J. Gonzalez-Jimenez,
**Efficient Reactive Navigation with Exact Collision Determination for 3D Robot Shapes**,  

[C1] M. Jaimez, M. Souiai, J. Gonzalez-Jimenez and D. Cremers,
**A Primal-Dual Framework for Real-Time Dense RGB-D Scene Flow**,  
*Proc. of the IEEE Int. Conf. on Robotics and Automation (ICRA)*, 2015.

[C2] M. Jaimez, M. Souiai, J. Stueckler, J. Gonzalez-Jimenez and D. Cremers,
**Motion Cooperation: Smooth Piece-Wise Rigid Scene Flow from RGB-D Images**,  