RGB-D SLAM Dataset and Benchmark List of Publications


[M1] R. Maier, Out-of-Core Bundle Adjustment for 3D Workpiece Reconstruction, Technische Universität München, Germany, September 2013.


[M1] C. Kerl,
Odometry from RGB-D Cameras for Autonomous Quadrocopters,
Technical University Munich, Germany, Nov. 2012.

[C1] N. Engelhard, F. Endres, J. Hess, J. Sturm and W. Burgard,
Real-time 3D visual SLAM with a hand-held camera,

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[C3] F. Steinbruecker, J. Sturm and D. Cremers,
Real-Time Visual Odometry from Dense RGB-D Images,
Workshop on Live Dense Reconstruction with Moving Cameras at the Intl. Conf. on Computer Vision (ICCV), 2011.